



In the name of God

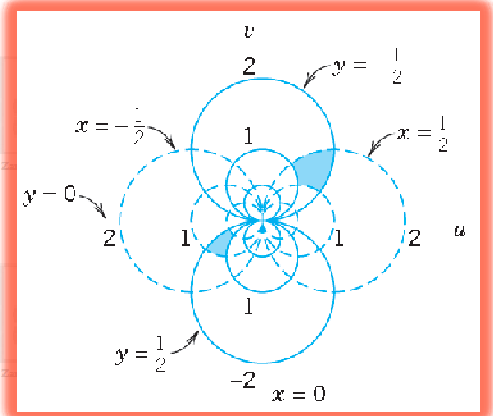
## Engineering Mathematics

### (Lecture # 23)


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# Conformal Mapping



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## Conformal Mapping




**Motivation:**

Conformal mappings are invaluable to the **engineer** and **physicist** as an **aid in solving problems** in potential theory. They are a standard method for **solving boundary value problems** in two-dimensional potential theory and yield rich applications in **electrostatics**, **heat flow**, and **fluid flow**.


The main feature of conformal mappings is that they are **angle-preserving**.

if  $f(z)$  is an **analytic** function, then the mapping given by  $w=f(z)$  is a **conformal mapping**, that is, it **preserves angles**, except at points where the derivative  $f'(z)$  is zero.

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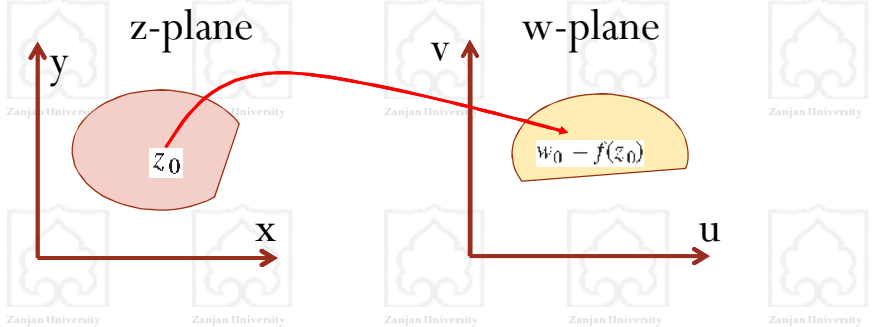
## Conformal Mapping



**Geometry of Analytic Functions:  
Conformal Mapping**

A complex function

(1)  $w = f(z) = u(x, y) - iv(x, y)$   $(z = x - iy)$



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### Conformal Mapping

**EXAMPLE 1** Mapping  $w = f(z) = z^2$

$z = re^{i\theta}$  and  $w = Re^{i\phi}$ ,  $\Rightarrow w = z^2 = r^2 e^{2i\theta}$

$R = r^2$        $\phi = 2\theta$

Figure 378 shows this for the region  $1 \leq |z| \leq \frac{3}{2}$ ,  $\pi/6 \leq \theta \leq \pi/3$ .

(z-plane)      (w-plane)

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### Conformal Mapping

$w = f(z) = u(x, y) + iv(x, y)$

In Cartesian coordinates we have  $z = x + iy$  and

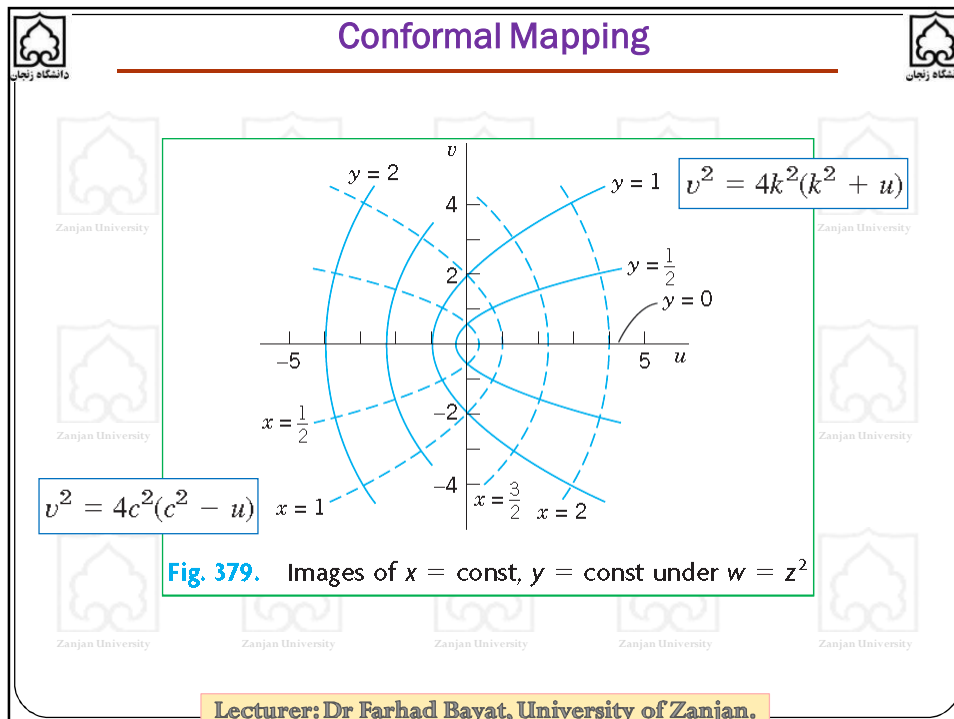
$u = \operatorname{Re}(z^2) = x^2 - y^2$ ,       $v = \operatorname{Im}(z^2) = 2xy$ .

vertical lines  $x = c = \text{const}$   $\Rightarrow \begin{cases} u = c^2 - y^2 \\ v = 2cy. \end{cases}$

we can eliminate  $y$ .  $\Rightarrow v^2 = 4c^2(c^2 - u)$

Similarly, horizontal lines  $y = k = \text{const}$   $\Rightarrow v^2 = 4k^2(k^2 + u)$

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A mapping  $w = f(z)$  is called **conformal** if it preserves angles between oriented curves in magnitude as well as in sense. Figure 380 shows what this means. The **angle**  $\alpha$  ( $0 \leq \alpha \leq \pi$ ) between two intersecting curves  $C_1$  and  $C_2$  is defined to be the angle between their oriented tangents at the intersection point  $z_0$ . And **conformality** means that the images  $C_1^*$  and  $C_2^*$  of  $C_1$  and  $C_2$  make the same angle as the curves themselves in both magnitude and direction.

Fig. 380. Curves  $C_1$  and  $C_2$  and their respective images  $C_1^*$  and  $C_2^*$  under a conformal mapping  $w = f(z)$

### THEOREM 1

#### Conformality of Mapping by Analytic Functions

The mapping  $w = f(z)$  by an analytic function  $f$  is conformal, except at **critical points**, that is, points at which the derivative  $f'$  is zero.

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**EXAMPLE 2 Conformity of  $w = z^n$**

The mapping  $w = z^n, n = 2, 3, \dots$ , is conformal, except at  $z = 0$ , where  $w' = nz^{n-1} = 0$ .

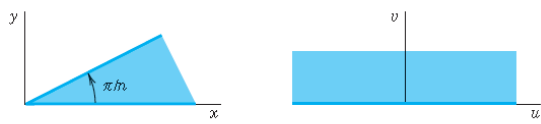


Fig. 382. Mapping by  $w = z^n$

**EXAMPLE 3 Mapping  $w = z + 1/z$ . Joukowski Airfoil**

$$w = u + iv = r(\cos \theta + i \sin \theta) + \frac{1}{r}(\cos \theta - i \sin \theta).$$

$$u = a \cos \theta, \quad v = b \sin \theta$$

where  $a = r + \frac{1}{r}, \quad b = r - \frac{1}{r}.$

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$$u = a \cos \theta, \quad v = b \sin \theta \quad \text{where} \quad a = r + \frac{1}{r}, \quad b = r - \frac{1}{r}.$$

circles  $|z| = r = \text{const} \neq 1 \rightarrow \frac{u^2}{a^2} + \frac{v^2}{b^2} = 1$

circle  $|z| = 1 = e^{i\theta} \rightarrow \text{segment } -2 \leq u \leq 2$

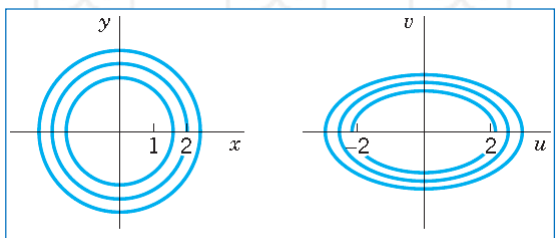


Fig. 383. Example 3

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The larger circle is mapped onto a *Joukowski airfoil*. The dashed circle passes through both 1 and -1 is mapped onto a curved segment.

**Fig. 384.** Joukowski airfoil

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**EXAMPLE 4** Conformality of  $w = e^z$

we have  $|e^z| = e^x$  and  $\text{Arg } w = y$

line  $x = x_0 = \text{const}$   $\Rightarrow$  circle  $|w| = e^{x_0}$

line  $y = y_0 = \text{const}$   $\Rightarrow$   $\arg w = y_0$ .

**Fig. 385.** Mapping by  $w = e^z$

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**Conformal Mapping**

The fundamental region  $-\pi < \text{Arg } z \leq \pi$  of  $e^z$

↓

entire  $w$ -plane without the origin  $w = 0$   
(because  $e^z = 0$  for no  $z$ ).

(z-plane)                      (w-plane)


**Fig. 386.** Mapping by  $w = e^z$

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**Conformal Mapping**

**Linear Fractional Transformations  
(Möbius Transformations)**

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**Linear fractional transformations (or Möbius transformations) are mappings**


(1)  $w = \frac{az + b}{cz + d} \quad (ad - bc \neq 0)$

where  $a, b, c, d$  are complex or real numbers. Differentiation gives


(2)  $w' = \frac{a(cz + d) - c(az + b)}{(cz + d)^2} = \frac{ad - bc}{(cz + d)^2}$

requirement  $ad - bc \neq 0$ .

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Special cases of (1) are

	$w = z + b$	<i>(Translations)</i>
	$w = az \quad \text{with }  a  = 1$	<i>(Rotations)</i>
(3)	$w = az + b$	<i>(Linear transformations)</i>
	$w = 1/z$	<i>(Inversion in the unit circle).</i>

$$w = \frac{az + b}{cz + d}$$

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**EXAMPLE 1** Properties of the Inversion  $w = 1/z$  (Fig. 387)

$z = re^{i\theta}$  and  $w = Re^{i\phi}$

$$Re^{i\phi} = \frac{1}{re^{i\theta}} = \frac{1}{r}e^{-i\theta}$$

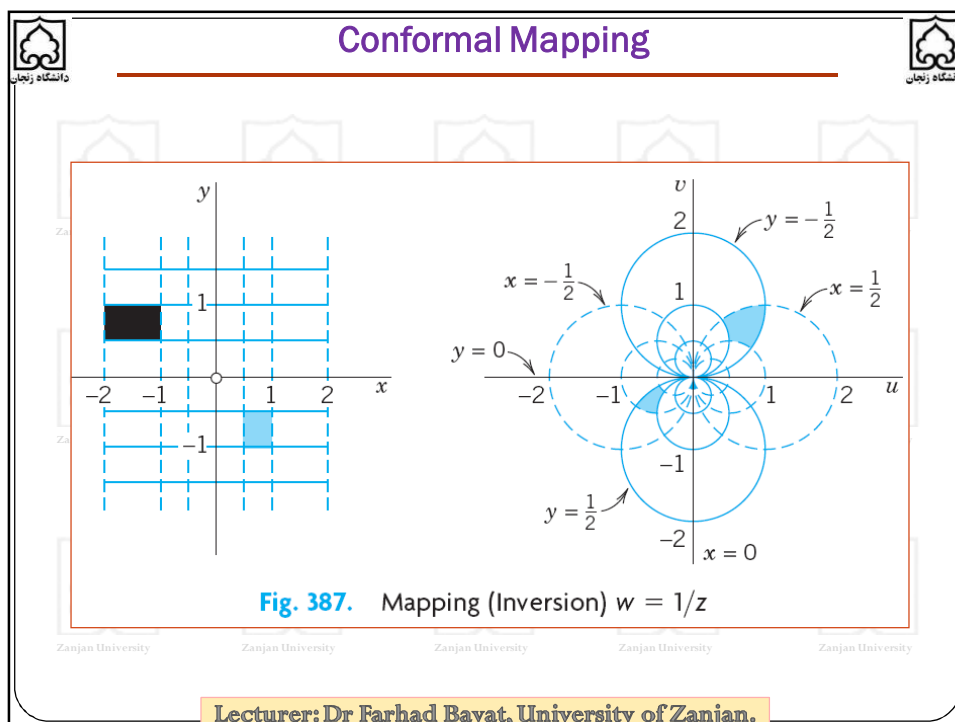
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$$R = \frac{1}{r}, \quad \phi = -\theta.$$

the unit circle  $|z| = r = 1$  is mapped onto the unit circle  $|w| = R = 1$ ;  $w = e^{i\phi} = e^{-i\theta}$ .

*$w = 1/z$  maps every straight line or circle onto a circle or straight line.*

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*Proof.* Every straight line or circle in the  $z$ -plane can be written

$$A(x^2 + y^2) + Bx + Cy + D = 0$$

$A = 0$  gives a straight line and  $A \neq 0$  a circle.

$$Az\bar{z} + B \frac{z + \bar{z}}{2} + C \frac{z - \bar{z}}{2i} + D = 0.$$

Substitution of  $z = 1/w$

$$A + B \frac{\bar{w} + w}{2} + C \frac{\bar{w} - w}{2i} + Dw\bar{w} = 0$$

$$A + Bu - Cv + D(u^2 + v^2) = 0.$$

a circle (if  $D \neq 0$ ) or a straight line (if  $D = 0$ ) in the  $w$ -plane.

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**Conformal Mapping**

**THEOREM 1**

**Three Points and Their Images Given**

Three given distinct points  $z_1, z_2, z_3$  can always be mapped onto three prescribed distinct points  $w_1, w_2, w_3$  by one, and only one, linear fractional transformation  $w = f(z)$ . This mapping is given implicitly by the equation

$$(2) \quad \frac{w - w_1}{w - w_3} \cdot \frac{w_2 - w_3}{w_2 - w_1} = \frac{z - z_1}{z - z_3} \cdot \frac{z_2 - z_3}{z_2 - z_1}.$$

(If one of these points is the point  $\infty$ , the quotient of the two differences containing this point must be replaced by 1.)

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**EXAMPLE 1** Mapping of a Half-Plane onto a Disk (Fig. 388)

Find the linear fractional transformation (1) that maps  $z_1 = -1$ ,  $z_2 = 0$ ,  $z_3 = 1$  onto  $w_1 = -1$ ,  $w_2 = -i$ ,  $w_3 = 1$ , respectively.

**Solution.**

$$\frac{w - (-1)}{w - 1} \cdot \frac{-i - 1}{-i - (-1)} = \frac{z - (-1)}{z - 1} \cdot \frac{0 - 1}{0 - (-1)},$$

$$w = \frac{z - i}{-iz + 1}.$$

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$z = x \rightarrow w = (x - i)/(-ix + 1)$ , thus  $|w| = 1$ , unit circle.

$z = i \rightarrow w = 0$ ,


$$w = \frac{z - i}{-iz + 1}.$$

Fig. 388. Linear fractional transformation in Example 1

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**EXAMPLE 2**    Occurrence of  $\infty$


Determine the linear fractional transformation that maps  $z_1 = 0, z_2 = 1, z_3 = \infty$  onto  $w_1 = -1, w_2 = -i, w_3 = 1$ , respectively.

**Solution.** From (2) we obtain the desired mapping


$$w = \frac{z - i}{z + i}.$$

(2)  $\frac{w - w_1}{w - w_3} \cdot \frac{w_2 - w_3}{w_2 - w_1} = \frac{z - z_1}{z - z_3} \cdot \frac{z_2 - z_3}{z_2 - z_1}.$

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**EXAMPLE 3**    Mapping of a Disk onto a Half-Plane

Find the linear fractional transformation that maps  $z_1 = -1, z_2 = i, z_3 = 1$  onto  $w_1 = 0, w_2 = i, w_3 = \infty$ , respectively, such that the unit disk is mapped onto the right half-plane. (Sketch disk and half-plane.)

**Solution.**

From (2) we obtain, after replacing  $(i - \infty)/(w - \infty)$  by 1,

$$w = -\frac{z + 1}{z - 1}.$$

(2)  $\frac{w - w_1}{w - w_3} \cdot \frac{w_2 - w_3}{w_2 - w_1} = \frac{z - z_1}{z - z_3} \cdot \frac{z_2 - z_3}{z_2 - z_1}.$

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### Mappings of disks onto disks

the unit disk in the  $z$ -plane is mapped onto the unit disk in the  $w$ -plane by

(3)  $w = \frac{z - z_0}{cz - 1}, \quad c = \bar{z}_0, \quad |z_0| < 1.$

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### EXAMPLE 5 Mapping of the Unit Disk onto the Unit Disk

Taking  $z_0 = \frac{1}{2}$  in (3), we obtain (verify!)

(3)  $w = \frac{z - z_0}{cz - 1}, \quad c = z_0, \quad \Rightarrow \quad w = \frac{2z - 1}{z - 2}$

**Fig. 389.** Mapping in Example 5

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EXAMPLE

$$w = i \frac{z - 1}{z + 1}$$

(z-plane)

(w-plane)

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EXAMPLE 6 Mapping of an Angular Region onto the Unit Disk

(z-plane)

(Z-plane)

(w-plane)

$$Z = z^3$$
$$w = i \frac{Z - 1}{Z + 1}$$

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**Questions? Discussion? Suggestions ?**



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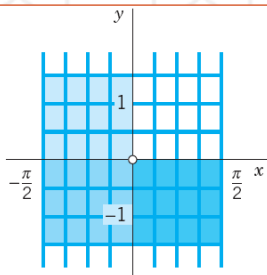
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**Sine Function.**

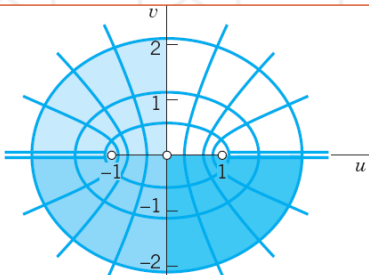
(1)  $w = u + iv = \sin z = \sin x \cosh y + i \cos x \sinh y$

Hence

(2)  $u = \sin x \cosh y, \quad v = \cos x \sinh y.$



(z-plane)



(w-plane)

**Fig. 391.** Mapping  $w = u + iv = \sin z$

